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# Functional-type a Posteriori Error Estimates for Boundary Element Methods

A 2D toy-project

Daniel Sebastian Särkisaari, 8. August 2018

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# Challenges

How a student with an analysis-background tries to do numerics.

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- Reminder (BEM)
- Setting
- Majorant
- Minorant
- First numerical results

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consists of the following parts:

 $\blacksquare \downarrow$  Mathematical model

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- $\blacksquare \downarrow$  Mathematical model
- $\downarrow$  Representation formula

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- $\blacksquare \downarrow$  Boundary integral equation
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- ↓ Discrete equations
- **\blacksquare**  $\downarrow$  Solution of the linear system
- $\blacksquare \downarrow$  Interpretation

Consider  $\Omega \subset \mathbb{R}^N$  a bounded Lipschitz domain

 $\Delta u = 0$  in  $\Omega$  $\gamma_0 u = g$  on  $\Gamma$ 

Fundamental solutions for Laplacian are e.g.:

$$\begin{split} G(x,y) &= -\frac{1}{2\pi} log |x-y| \quad \text{for } \mathbb{R}^2\\ G(x,y) &= & \frac{1}{4\pi |x-y|} \qquad \text{for } \mathbb{R}^3 \end{split}$$

To present the solution of the PDE in the domain by means of boundary potentials, we have for  $x \in \mathbb{R}^N \setminus \Gamma$ :

$$u(x) = \int_{\Gamma} \partial_{n(y)} G(x, y) \left[ u(y) \right]_{\Gamma} d\sigma(y) - \int_{\Gamma} G(x, y) \left[ \partial_{n} u(y) \right]_{\Gamma} d\sigma(y)$$
(1)

where 
$$[v(x)]_{\Gamma} := v_{|\mathbb{R}^N \setminus \Omega}(x) - v_{|\bar{\Omega}}(x)$$
  $(x \in \Gamma)$ 

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$$u(x) = -\int_{\Gamma} \partial_{n(y)} G(x, y) u(y) \, d\sigma(y) + \int_{\Gamma} G(x, y) \partial_n u(y) \, d\sigma(y) \quad (x \in \Omega).$$
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<sup>(2)</sup>

2. Supposing  $[u]_{\Gamma} = 0$ , one obtaines a single layer representation

$$u(x) = \int_{\Gamma} G(x, y)\psi(y) \, d\sigma(y) =: \tilde{V}(\psi)(x) \quad (x \in \Omega)$$
(3)

with an unknown density  $\psi$ . ( $\tilde{V}$ :  $H^{-1/2}(\Gamma) \rightarrow H^1(\Omega)$  bounded linear operator)

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3. Supposing  $[\partial_n u]_{\Gamma} = 0$ , one obtaines a **double layer representation** 

$$u(x) = \int_{\Gamma} v(y) \partial_{n(y)} G(x, y) \, d\sigma(y) =: \tilde{K}(v)(x) \quad (x \in \Omega)$$
<sup>(4)</sup>

with an unknown density  $v. (\tilde{K} \colon H^{1/2}(\Gamma) \to H^1(\Omega)$  bounded linear operator.)

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2. Supposing  $[u]_{\Gamma} = 0$ , one obtaines a single layer representation

$$u(x) = \int_{\Gamma} G(x, y)\psi(y) \, d\sigma(y) =: \tilde{V}(\psi)(x) \quad (x \in \Omega)$$
(6)

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**3.** Supposing  $[\partial_n u]_{\Gamma} = 0$ , one obtaines a **double layer representation** 

$$u(x) = \int_{\Gamma} v(y)\partial_n(y)G(x,y) \, d\sigma(y) =: \tilde{K}(v)(x) \quad (x \in \Omega)$$
(7)

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 $\rightarrow$  bounded linear operators

 $V := \gamma_0 \circ \tilde{V} \colon H^{-1/2}(\Gamma) \to H^{1/2}(\Gamma) \qquad \qquad K := \gamma_0 \circ \tilde{K} \colon H^{1/2}(\Gamma) \to H^{1/2}(\Gamma)$ 

1. The idea of a direct method is to approximate the Neumann-data given the Dirichlet-data. The equation to solve here is:

$$V\phi = (\frac{1}{2} + K)g$$
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The single layer potential Vφ(x) := ∫<sub>Γ</sub> G(x, y)φ(y) dσ(y) is continous across Γ. The equation to solve here is:

$$V\phi = g$$
 in  $H^{-1/2}(\Gamma)$ 



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1. replace boundary  $\Gamma$  by some polygon  $\Gamma_h$ 

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- 4.  $h := \max_i h_i$   $h_{\min} := \min_i h_i$
- 5. trial space  $S_h^0(\Gamma) := \operatorname{span}\{\chi_i\}_{i=1,\ldots,n} \subset H^{-1/2}(\Gamma), \dim S_h^0(\Gamma) = n$

#### Setting - Symm's integral equation



Consider  $\Omega \subset \mathbb{R}^2$  a polygon

$$\Delta u = 0$$
 in  $\Omega$   
 $\gamma_0 u = g$  on  $\Gamma$ 

 $\Delta : H^{1}(\Omega) \to H^{-1}(\Omega)$  the Laplace operator,  $\gamma_{0} : H^{1}(\Omega) \to H^{1/2}(\Gamma)$  the Dirichlet trace operator, *g* some function determined by the given Dirichlet data  $u|_{\Gamma} \in H^{1/2}(\Gamma)$ .

Aim at indirect boundary integral equation formulation, based on the single layer potential

$$u(x) = \int_{\Gamma} G(x, y) w(y) d\Gamma_y, \quad x \in \Omega \subset \mathbb{R}^2$$

where  $G(x, y) = -\frac{1}{2\pi} \ln |x - y|$  the fundamental solution in  $\mathbb{R}^2$ .

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#### Setting - Variational formulation

Find  $\phi \in H^{-1/2}(\Gamma)$  such that

$$\langle \phi', V \phi \rangle = \langle \phi', g \rangle \quad \forall \phi' \in H^{-1/2}(\Gamma),$$

or respectively, find  $\phi_h \in S_h^0(\Gamma)$  such that

$$\langle \phi'_h, V\phi_h \rangle = \langle \phi'_h, g \rangle \quad \forall \phi'_h \in S^0_h(\Gamma).$$
 (8)

where  $\langle \cdot, \cdot \rangle := \langle \cdot, \cdot \rangle_{H^{-1/2}(\Gamma) \times H^{1/2}(\Gamma)}$  extension of the  $L^2$  scalar product. Set  $u_h = \tilde{V}\phi_h$ . Then  $\Delta u_h = 0$  but does not fulfill the boundary condition  $\gamma_0 u_h = g$  on  $\Gamma$ .

#### **PROBLEMS:**

- 1. Norms of "BEM-typical" non-integer Sobolev-spaces are non-local: "localization techniques" become necessary, e.g. one needs some *interpolation estimate*
- "Many of residual-based methods use Hölder-, Triangle and Minckowsky-Inequality which lead to overestimation."
- the error estimates refer to the neumann jump / density function, not towards the global reconstruction

$$F(\phi - \phi_h) = ||\phi - \phi_h||_{H^{-1/2}(\Gamma)}$$
 vs.  $F(u - v) = ||\nabla(u - v)||_{L^2(\Omega)}$ 

It is by triangle inequality

$$||\nabla(u-u_h)||_{L^2(\Omega)} \leq \inf_{\substack{\nu \in H^1(\Omega) \\ \gamma_0 \nu = q}} ||\nabla(\nu-u_h)||_{L^2(\Omega)}.$$

"Shift the problem to the boundary": the energy error is equal to the quantity

$$\varepsilon(u_h) := \inf_{\substack{w \in H^1(\Omega), \\ \gamma_0 w = g - \gamma_0 u_h}} ||\nabla w||$$

TASK: How to estimate  $\varepsilon(u_h)$  via known  $e := g - \gamma_0 u_h$  on the boundary with minimal expenditures?

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#### IDEA:

Find a "good" extension  $\Pi e \colon H^{1/2}(\partial \Omega) \to H^1(\Omega)$ , the norm of which

1. does not seriously overestimate

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2. is not expensive to compute (rather than computing the infimum, choose "good"w)

In the case of BEM one easily computable harmonic extension is:

- Set  $e_i := g \gamma_0 u_h$  on  $\Gamma_i$  and find  $\Pi_i : H^{1/2}(\Gamma_i) \to H^1(\hat{\Omega}_i)$  s.t.:
  - 1. the restriction of *w* to individual triangles in  $\hat{\Omega}_i$  is linear,

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$$\varepsilon(u_h) = \inf_{\substack{w \in H^1(\Omega), \\ \gamma_0 w = g - \gamma_0 u_h}} ||\nabla w||$$

Then the respective Dirichlet integral is

$$I(e_i) = || \nabla \Pi_i(e_i) ||_{\hat{\Omega}_i}$$

and therefore

$$\varepsilon^2(u_h) = \sum_{i=1}^n l^2(e_i).$$

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### **Numerical "results" –** majorant with uniform meshrefinement

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The simplest minorant (only simplicial domains) results from the Poincaré-type inequality

$$||w||_{L^{2}(\Gamma)} \leq C(\Gamma, \Omega)||\nabla w||_{L^{2}(\Omega)}$$

for functions  $w \in H^1(\Omega)$  with zero mean trace on  $\Gamma$ .

NOTE: our approximation  $u_h$  satisfies  $\int_{\Gamma} (g - \gamma_0 u_h) d\Gamma = 0$  ( $1 \in S_h^0(\Gamma)$  and weak formulation) so we arrive at

$$C^{-1}(\Gamma,\Omega) ||\boldsymbol{e}||_{\Gamma} \leq ||\nabla(\boldsymbol{u}-\boldsymbol{u}_{h})||_{\Omega}$$

where the left hand side is fully computable.

S. Repin, A. Nazarov Exact Constants in Poincaré-Type Inequalities for Functions with Zero Mean Boundary Traces, Math. Meth. Appl. Sci., 2014, vol. 38, no. 15, pp. 3195-3207. and

S. Matculevich, S. Repin. Explicit Constants in Poincaré-Type Inequalities for Simplicial Domains and Application to A Posteriori Estimates. Volume 16, Issue 2 (Apr. 2016

#### **Minorant 2nd**

In Hilbert spaces H we have

$$|\tilde{h}||_{H}^{2} = \max_{h \in H} (2\langle \tilde{h}, h \rangle_{H} - ||h||_{H}^{2})$$

and therefore defining  $e := g - \gamma_0 u_h$ 

$$\begin{aligned} ||\nabla(u-u_h)||_{L^2(\Omega)} &= \max_{\tau_0 \in L^2(\Omega)} 2 \int_{\Omega} \nabla(u-u_h) \cdot \tau_0 - ||\tau_0||_{L^2(\Omega)}^2 \\ &\geq \max_{\tau_0 \in D_0(\Omega)} 2 \int_{\Omega} \nabla(u-u_h) \cdot \tau_0 - ||\tau_0||_{L^2(\Omega)}^2 \\ &\geq 2 \int_{\Gamma} e \tau_0 \cdot n - ||\tau_0||_{L^2(\Omega)}^2 \end{aligned}$$

It holds equality if  $\tau_0 = \nabla(u - u_h) \in D_0 = H(div; \Omega; div = 0)$ .

$$||\nabla(u-u_{\hbar})||_{L^{2}(\Omega)} \geq 2\int_{\Gamma} e \operatorname{curl}_{Z} W \cdot n - ||\nabla W||_{L^{2}(\Omega)}^{2}$$

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It holds equality if  $\tau_0 = \nabla(u - u_h) \in D_0 = H(div; \Omega; div = 0).$ 

$$\rightarrow ||\nabla (u - u_h)||_{L^2(\Omega)} \ge 2 \int_{\Gamma} e \operatorname{curl}_{Z} W \cdot n - ||\nabla W||_{L^2(\Omega)}^2$$

# BACK TO THE MAJORANT!

# **Numerical "results"** – majorant with adaptive mesh-refinement





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#### Numerical "results" - all with uniform mesh-refinement





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• use Green's second identity (for direct method) to compute  $H^1$  seminorm of  $u - u_h$ 

- use Green's second identity (for direct method) to compute  $H^1$  seminorm of  $u u_h$
- use *P*<sup>2</sup> elements for interpolating the "error nodes":

$$||\nabla(u - l_h u)||_{L^2(T)} \le h_T ||D^2 u||_{L^2(T)}$$

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Daniel, learn proper programming!

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- further discussions now!

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$$||\nabla(u - I_h u)||_{L^2(T)} \le h_T ||D^2 u||_{L^2(T)}$$

- Daniel, learn proper programming!
- further discussions now!

#### THANKS FOR YOUR ATTENTION!

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