

## **Purpose:**

How to train an MLP neural network in MATLAB environment!

**that is**

For good computations,  
we need good formulae  
for good algorithms;  
and good visualization  
for good illustration  
of good methods  
and successful applications!

### Course structure:

- lectures 7 weeks 2 h/week: 22.10.–3.12. Ag Beeta (TK, room Ag C415.1)
- exercises 7 weeks 4 h/week: 23.10.–12.12. (EH, room Ag C424.1):
  1. Wednesday 8–10 Ag B212.1 (until 4.12.2002 saakka),
  2. Thursday 14–16 Ag B211.1 (until 12.12.2002, week 50 concerning seminar works)
- preparation of seminar works, period III 2003, weeks 2–9:
  1. weekly tutoring session on Thursday 14–16 Ag B212.1
- presentation and evaluation seminar 6–8 h: week 10, 2003.
- final examination by the end of period III 2003
- course evaluation:

from the obligatory seminar work 3–12 points (coinciding with the grades 1- – 3)  
for the final examination: all other groups evaluate the work and presentation of one group, Erkki&Tommi can increase or decrease this evaluation by  $+ - \frac{1}{2}$

## **Lecture Topics:**

- Introduction, about matrices and vectors
- Introduction to MATLAB graphics
- Introduction to Optimization
- MLP-networks I–III
- API/MEX and GUIs for MATLAB
- Seminar works

## About MATLAB:

- Matrix Laboratory
- astonishingly complete environment for computational prototyping
- good build-in graphics
- possibility to link own external (sub)routines in C and Fortran
- poor man's version OCTAVE (<http://www.octave.org/>)
- extension possibilities using multiple *toolboxes*
- for our purposes:
  - definition of matrices and utilization of basic operations in linear algebra
  - fundamentals of optimization methods and their usage
  - data manipulation
  - testing and visualization of implemented operations using MATLAB graphics

## About matrices and vectors (in MATLAB):

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1m} \\ a_{21} & a_{22} & \dots & a_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nm} \end{bmatrix} \in \mathbf{R}^{n \times m}$$

can represent, e.g.

$$\begin{cases} a_{11}x_1 + \dots + a_{1n}x_n = y_1 \\ \vdots + \dots + \vdots = \vdots \\ a_{n1}x_1 + \dots + a_{nn}x_n = y_n \end{cases} \Leftrightarrow \mathbf{Ax} = \mathbf{y}$$

or

$$\mathbf{A} = \begin{bmatrix} z(x_1, y_1) & \dots & z(x_n, y_1) \\ \vdots & \ddots & \vdots \\ z(x_1, y_n) & \dots & z(x_n, y_n) \end{bmatrix}, \quad \mathbf{X} = \begin{bmatrix} x_1 & \dots & x_n \\ \vdots & \ddots & \vdots \\ x_1 & \dots & x_n \end{bmatrix} \quad \text{and} \quad \mathbf{Y} = \begin{bmatrix} y_1 & \dots & y_1 \\ \vdots & \ddots & \vdots \\ y_n & \dots & y_n \end{bmatrix},$$

and as a linear transformation  $\mathbf{A} : \mathbf{R}^m \rightarrow \mathbf{R}^n$  simply means

$$\mathbf{y} = \mathbf{Ax} \Leftrightarrow y_i = \sum_{j=1}^m a_{ij} x_j.$$

### Matrix operations (in MATLAB):

**(Identity matrix:  $B = I \Leftrightarrow b_{ii} = 1 \forall i; b_{ij} = 0 \forall i \neq j$  (MATLAB `b=eye(n)`))**

**Transpose:  $B = A^T \Leftrightarrow b_{ij} = a_{ji}$  (MATLAB `b=a'`).**

**Scalar multiplication:  $B = tA \Leftrightarrow b_{ij} = ta_{ij}$  (MATLAB `b=t*a`).**

**Addition:  $C = A + B \Leftrightarrow c_{ij} = a_{ij} + b_{ij}$  (MATLAB `c=a+b`).**

**Matrix multiplication:  $C = AB \Leftrightarrow c_{ij} = \sum_k a_{ik}b_{kj}$  (MATLAB `c=a*b`).**

**Componentwise multiplication:  $c_{ij} = a_{ij}b_{ij}$  (MATLAB `c=a.*b`).**

**Componentwise quotient:  $c_{ij} = \frac{a_{ij}}{b_{ij}}$  ( $b_{ij} \neq 0$ ) (MATLAB `c=a./b`).**

**Matrix inverse:  $B = A^{-1} \Leftrightarrow BA = AB = I$  (MATLAB `b=inv(a)`).**

Note: only when  $A^{-1}$  exists, i.e.  $A$  is nonsingular (MATLAB `det(a) ~= 0`).

### Solution of linear equations:

left inverse:  $Ax = y \Leftrightarrow x = A^{-1}y$  (MATLAB `x=a\y`),

right inverse:  $xA = y \Leftrightarrow x = yA^{-1}$  (MATLAB `x=y/a`).